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ATTI ACCADEMIA NAZIONALE DEI LINCEI  
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# RENDICONTI

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## Sufficient Conditions for Nonoscillation of n-th Order Nonlinear Differential Equations

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**Equazioni differenziali ordinarie.** — *Sufficient Conditions for Nonoscillation of  $n$ -th Order Nonlinear Differential Equations* (\*). Nota di LU-SAN CHEN, presentata (\*\*) dal Socio G. SANSONE.

RIASSUNTO. — Si danno condizioni sufficienti perché tutte le soluzioni di una classe di equazioni differenziali nonlineari siano nonoscillatorie.

I. INTRODUCTION

In the paper [1], Graef and Spikes have given sufficient conditions for every solution of the nonlinear differential equation

$$[l(t)x'(t)]' + p(t)g(x(t), x'(t)) = h(t; x(t), x'(t))$$

to be nonoscillatory. Those results are obtained in terms of integral conditions on  $h(t; x(t), x'(t))$  and  $p(t)$ . The purpose of the present paper is to give sufficient conditions for nonoscillation of  $n$ -th order nonlinear differential equations of the form

$$(*) \quad [l(t)x^{(n-1)}(t)]' + p(t)g(x(t), x'(t), \dots, x^{(n-1)}(t)) = h(t; x(t), \dots, x^{(n-1)}(t)), \quad (n \geq 2)$$

which contains a damping term involving the  $(n-1)$ -th derivative of the unknown function, where

- (i)  $l : [t_0, \infty) \rightarrow (0, \infty)$  is continuous,  $t_0 \geq 0$ ,
- (ii)  $p : [t_0, \infty) \rightarrow (0, \infty)$  is continuous,
- (iii)  $g : \mathbb{R}^n \rightarrow \mathbb{R} = (-\infty, \infty)$  is continuous and satisfies  $y_1 g(y_2, \dots, y_n) > 0$  for  $y_1 (\neq 0)$  and for any  $t (\geq t_0)$ ,
- (iv)  $h : [t_0, \infty) \times \mathbb{R}^n \rightarrow \mathbb{R}$  is continuous.

In the sequel, all functions considered will be assumed continuous on their domains, and the existence of solutions of (\*), which are valid for all large  $t$ , will be assumed without further mention. A solution of (\*) is a function  $x(t) \in C^n([t_x, \infty), \mathbb{R})$ , which satisfies (\*) on  $[t_x, \infty)$  ( $t_x \geq t_0$  ( $t_0$  fixed) and depending on the particular solution  $x(t)$ ). Denote by  $U$  the family of all such solutions of (\*). A function  $x(t) \in U$  is said to be "nonoscillatory" if there exists  $t_1 (\geq t_x)$  such that  $x(t) \neq 0$  for  $t \geq t_1$  and it is said to be bounded if  $|x(t)| \leq k$  for every  $t \in [t_x, \infty)$ , where  $k$  is a positive constant.

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## 2. Sufficient conditions for nonoscillation.

To prove the main results we need the following Lemma.

LEMMA (Kiguradze [2], [3]). *Let  $u$  be a positive  $\nu$ -times continuously differentiable function on an interval  $[t_0, \infty)$ . If  $u^{(\nu)}$  is of constant sign and is not identically zero for all large  $t$ , then there exist a  $T (\geq t_0)$  and an integer  $l, 0 \leq l \leq \nu$  with  $\nu + l$  odd if  $u^{(\nu)} \leq 0$ ,  $\nu + l$  even if  $u^{(\nu)} \geq 0$  and such that for every  $t \geq T$ ,*

$$l > 0 \quad \text{implies} \quad u^{(k)} > 0 \quad (k = 0, 1, \dots, l-1)$$

and

$$l \leq \nu - 1 \quad \text{implies} \quad (-1)^{l+k} u^{(k)}(t) > 0, \quad (k = l, l+1, \dots, \nu-1).$$

We make use of the following conditions:

( $c_1$ ) for every  $x(t) \in C^n [t_0, \infty)$  there exists a constant  $M$  such that

$$g(x(t), x'(t), \dots, x^{(n-1)}(t)) \leq M \quad \text{for all large } t;$$

( $c_2$ ) for every  $x(t) \in C^n [t_0, \infty)$  there exists a constant  $L$  such that

$$L \leq g(x(t), x'(t), \dots, x^{(n-1)}(t))$$

for all large  $t$ ;

( $c_3$ ) for every  $x(t) \in C^n [t_0, \infty)$  there exists a real-valued function  $h_1(t)$  on  $[t_0, \infty)$  such that

$$h_1(t) \leq h(t; x(t), x'(t), \dots, x^{(n-1)}(t))$$

for all large  $t$ ;

( $c_4$ ) for every  $x(t) \in C^n [t_0, \infty)$  there exists a real-valued function  $h_2(t)$  on  $[t_0, \infty)$  such that

$$h(t; x(t), x'(t), \dots, x^{(n-1)}(t)) \leq h_2(t)$$

for all large  $t$ .

THEOREM 1. *Suppose that conditions ( $c_1$ ) and ( $c_3$ ) are satisfied. Moreover, assume that*

$$(I) \quad \int_{t_0}^{\infty} [h_1(s) - Mp(s)] ds = +\infty.$$

*Then every  $x(t) \in U$  is nonoscillatory.*

*Proof.* We will write equation (\*) as the system

$$(**) \quad \begin{cases} x^{(n-1)} = \frac{y}{l(t)}, \\ y' = h(t; x(t), \dots, x^{(n-1)}(t)) - p(t)g(x(t), \dots, x^{(n-1)}(t)). \end{cases}$$

Suppose there is a solution  $(x(t), y(t))$  of (\*\*).

Integrating the second equation in (\*\*) from  $t_0$  to  $t$ , we have

$$y(t) = y(t_0) + \int_{t_0}^t h(s; x(s), \dots, x^{(n-1)}(s)) ds - \int_{t_0}^t p(s) g(x(s), \dots, x^{(n-1)}(s)) ds.$$

Then, from  $(c_1)$ ,  $(c_3)$  and (I) we have

$$y(t) \geq y(t_0) + \int_{t_0}^t [h_1(s) - Mp(s)] ds \rightarrow +\infty \quad \text{as } t \rightarrow \infty.$$

Hence, there exists  $t_1 \geq t_0$  such that  $y(t) \geq 0$  for  $t \geq t_1$ , which, in view of the first equation in (\*\*), implies  $x^{(n-1)}(t) \geq 0$  for  $t \geq t_1$ . Hence, from the Lemma, there exist a  $T (\geq t_1)$  and an integer  $l (0 \leq l \leq n-1)$  with  $n-1+l$  even, such that for every  $t \geq T$

$$\begin{aligned} x^{(k)}(t) &> 0, & k = 0, 1, \dots, l-1, \\ (-1)^{l+k} x^{(k)}(t) &> 0, & k = l, l+1, \dots, n-2. \end{aligned}$$

From this we conclude that  $x'(t) > 0$  for every  $t \geq T$  and so  $x(t)$  is nonoscillatory. Here no assumption is made about the sign of  $M$ .

The proof of following theorem follows from a procedure quite similar to the proof of Theorem 1. The details may be omitted.

**THEOREM 2.** *Suppose that conditions  $(c_2)$  and  $(c_4)$  are satisfied. Moreover, assume that*

$$\int_{t_0}^{\infty} [h_2(s) - Lp(s)] ds = -\infty.$$

*Then every  $x(t) \in U$  is nonoscillatory, where no assumption is made about the sign of  $L$ .*

**THEOREM 3.** *For the equation (\*), subject to the condition  $(c_3)$ , suppose that  $g(y_1, y_2, \dots, y_n)$  is bounded from above whenever the first variable is bounded. Moreover, assume that*

$$\int_{t_0}^{\infty} [h_1(s) - \lambda_1 p(s)] ds = +\infty \quad \text{for every } \lambda_1.$$

*Then every bounded  $x(t) \in U$  is nonoscillatory.*

*Proof.* Suppose that  $x(t) \in U$  is bounded with the property  $0 < x(t) < k$  for every  $t \geq t_0$ . Then there exists a constant  $\lambda_1$  such that  $0 < g(x(t), \dots, x^{(n-1)}(t)) < \lambda_1$  for every  $t \geq t_0$ . Hence we obtain

$$y(t) \geq y(t_0) + \int_{t_0}^t [h_1(s) - \lambda_1 p(s)] ds \rightarrow +\infty \quad \text{as } t \rightarrow \infty,$$

and the desired conclusion follows as in Theorem 1. Thus  $x(t)$  is nonoscillatory. A similar proof holds in the case  $-k < x(t) < 0$  ( $k =$  a positive constant) and our theorem is established.

**THEOREM 4.** *For the equation (\*), subject to the condition (c<sub>4</sub>), suppose that  $g(y_1, y_2, \dots, y_n)$  is bounded from below whenever the first variable is bounded. Moreover, assume that*

$$\int_{t_0}^{\infty} [h_2(s) - \lambda_2 p(s)] ds = -\infty \quad \text{for every } \lambda_2.$$

*Then every bounded  $x(t) \in U$  is nonoscillatory.*

*Proof.* As  $g(y_1, y_2, \dots, y_n)$  is bounded from below, i.e.  $\lambda_2 < g(y_1, y_2, \dots, y_n)$ , the theorem follows immediately from Theorem 3.

**THEOREM 5.** *Suppose the condition (c<sub>3</sub>), in addition assume that there exists a constant  $\mu$  satisfying*

$$|g(y_1, y_2, \dots, y_n)| \leq \mu \quad \text{for every } t \geq t_0$$

*and*

$$\int_{t_0}^{\infty} [h_1(s) - \mu |p(s)|] ds = +\infty.$$

*Then every  $x(t) \in U$  is nonoscillatory.*

*Proof.* The proof is obvious.

**THEOREM 6.** *In Theorem 5, replace (c<sub>3</sub>) by (c<sub>4</sub>) and, moreover, suppose that*

$$\int_{t_0}^{\infty} [h_2(s) + \mu |p(s)|] ds = -\infty.$$

*Then every  $x(t) \in U$  is nonoscillatory.*

*Proof.* This follows immediately from Theorem 5.

The proofs of the following theorems are similar to the proofs of the above ones and will be omitted.

THEOREM 7. Assume that the condition  $(c_3)$  is satisfied and that  $g(y_1, y_2, \dots, y_n)$  is bounded whenever the first variable is bounded. Moreover, suppose

$$\int_{t_0}^{\infty} [h_1(s) - \tau |p(s)|] ds = +\infty \quad \text{for every } \tau > 0.$$

Then every bounded  $x(t) \in U$  is nonoscillatory.

THEOREM 8. In Theorem 7, replace  $(c_3)$  by  $(c_4)$  and moreover, assume

$$\int_{t_0}^{\infty} [h_2(s) + \tau |p(s)|] ds = -\infty \quad \text{for every } \tau > 0.$$

Then every bounded  $x(t) \in U$  is nonoscillatory.

Remark 1. The particular case  $n = 2$  is due to Graef and Spikes [1].

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