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The skew matrix equation $X'_n \cdots X'_1 A X_1 \cdots X_n = B$

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Teorie combinatorie. — *The skew matrix equation* $X_n' \cdots \cdots X_1' A X_1 \cdots X_n = B$. Nota di A. ALLAN RIVELAND e A. DUANE PORTER, presentata (*) dal Socio B. SEGRE.

RIASSUNTO. — La suddetta equazione matriciale viene studiata su di un campo finito, ottenendo risultati che estendono ed in parte correggono proprietà precedentemente date in argomento da altri Autori.

1. INTRODUCTION

All matrices under consideration will have entries in the Galois field $GF(q)$, $q = p^f$, p an odd prime. X' will denote the matrix transpose of the matrix X . In [2] Leonard Carlitz determined the number of $2m \times t$ matrices X for which

$$(1.1) \quad X'AX = B$$

where A and B are fixed skew matrices ($A' = -A$, $B' = -B$), A nonsingular of order $2m$, B of order t and rank $2r$, $r \leq m$. Related counting problems have been investigated in [1], [3], [4], and [6]. In this note we wish to generalize the results in [2] by counting the number of solutions X_1, X_2, \dots, X_n to the matrix equation

$$(1.2) \quad X_n' \cdots X_1' A X_1 \cdots X_n = B$$

where A and B are skew matrices and the dimension of all matrices are such that matrix multiplication is defined. Similar generalizations of [4] and [6] have been performed by Porter in [7] and [8] respectively.

We also correct a minor error in one of Carlitz's formulas in [2] and correct the main theorem in [5] which was dependent upon the faulty formula in [2].

2. NOTATION AND PRELIMINARIES

It is well known that if A is a skew matrix of rank $2r$ then there exists a nonsingular matrix P over $GF(q)$ for which

$$P'AP = \text{diag}(E_1, \dots, E_r, 0, \dots, 0) \quad , \quad E_i = \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix}, \quad i = 1, \dots, r.$$

We will reserve the notation $C(t, 2r)$ to denote the above described canonical form for a $t \times t$ skew matrix of rank $2r$.

(*) Nella seduta del 10 giugno 1976.

It is easy to show that the number of solutions to the matrix equation (1.2) remains invariant if the matrices A and B are replaced by their respective canonical forms. Hence the problem posed in the previous section may be solved by finding the number of solutions to the matrix equation

$$(2.1) \quad X'_n \cdots X'_1 C(d_0, 2m) X_1 \cdots X_n = C(d_n, 2r)$$

where each X_i is of dimension $d_{i-1} \times d_i$, $i = 1, \dots, n$. We denote this number by $N(d_0, \dots, d_n; 2m, 2r)$. With this notation $N(2m, t; 2m, 2r)$ will represent the number of solutions to (1.1) which was determined by Carlitz [2; Theorem 5, denoted $Z_t(A, B)$].

It is clear that $N(d_0, \dots, d_n; 2m, 2r) = 0$ if $\min(d_1, \dots, d_n, 2m) < 2r$. Hence without loss of generality we can require that

$$(2.2) \quad 2r \leq \min(d_1, \dots, d_n, 2m).$$

Although it is not needed here, it is easy to show that (2.2) is also a sufficient condition for the existence of a solution to (2.1).

Carlitz [2; Theorem 3] determined the number $S(t, 2r)$ of $t \times t$ skew matrices over $GF(q)$ of rank $2r$. He obtained

$$(2.3) \quad S(t, 2r) = q^{r(r-1)} \prod_{i=0}^{2r-1} (q^{t-i} - 1) / \prod_{i=1}^r (q^{2i} - 1), \quad r > 0.$$

3. THE MAIN THEOREM

Before stating main result we need the following:

LEMMA 1. For $n > 1$

$$\begin{aligned} N(d_0, \dots, d_n; 2m, 2r) &= \\ &= \sum_{k \in M} N(d_0, \dots, d_{n-1}; 2m, k) S(d_{n-1}, k) N(d_{n-1}, d_n; k, 2r) \end{aligned}$$

where M is the set of even integers k for which $2r \leq k \leq \min(d_1, \dots, d_{n-1}, 2m)$ and S is given by (2.3).

Proof. To count solutions to (2.1) under condition (2.2) we may count solutions to the matrix equation

$$(2.4) \quad X'_{n-1} \cdots X'_1 C(d_0, 2m) X_1 \cdots X_{n-1} = D,$$

then count solutions to the matrix equation

$$(2.5) \quad X'_n D X_n = C(d_n, 2r),$$

then multiply these numbers, and sum as D ranges over all possible $d_{n-1} \times d_{n-1}$ matrices. But equations (2.4) and (2.5) both have solutions only if D is skew and has even rank k where $2r \leq k \leq \min(d_1, \dots, d_{n-1}, 2m)$. In other words we sum as D ranges over M where M is as described in Lemma 1.

For each $k \in M$ there will be exactly $S(d_{n-1}, k)$ skew $d_{n-1} \times d_{n-1}$ matrices of rank k . Each of these matrices has canonical form $C(d_{n-1}, k)$ and gives rise to

$$N(d_0, \dots, d_{n-1}; 2m, k) N(d_{n-1}, d_n; k, 2r)$$

solutions of (2.1). This product is obtained by replacing D in (2.4) and (2.5) by its canonical form, counting solutions to the resulting equations and multiplying. Therefore, each $k \in M$ gives rise to

$$S(d_{n-1}, k) N(d_0, \dots, d_{n-1}; 2m, k) N(d_{n-1}, d_n; k, 2r)$$

solutions. Summing as k ranges over M will produce the desired conclusion.

The main theorem follows directly from the preceding lemma and mathematical induction. The proof is omitted.

THEOREM 1. *The number $N = N(d_0, \dots, d_n; 2m, 2r)$, $n > 1$, of solutions X_1, \dots, X_n of the matrix equation (2.1) under condition (2.2) is given by*

$$N = \sum_{i_j \in M_j} N(d_0, d_1; 2m, i_1) \prod_{k=1}^{n-1} S(d_k, i_k) N(d_k, d_{k+1}; i_k, i_{k+1}),$$

$$j = 1, \dots, n-1$$

where S is given in (2.3) and M_j is the set of even integers i_j for which $2r \leq i_j \leq \min(2m, d_1, \dots, d_j)$, $j = 1, \dots, n-1$, $i_n = 2r$.

Using [2; Theorem 5] (subject to the correction indicated in Theorem 2 of this paper) it would now be possible to express N in terms of the variables d_0, \dots, d_1, r , and m but we will not take the space to do so.

It should be noted that Carlitz's formula for $N(2m, t; 2m, 2r)$ which counts solutions to (1.1) required that the matrix A be nonsingular. However as Carlitz observes, this requirement causes no loss of generality. Indeed, it is easy to show that

$$N(p, t; 2m, 2r) = q^{t(p-2m)} N(2m, t; 2m, 2r)$$

so if the central matrix A in (1.1) is not already nonsingular the problem is easily reduced to one in which this is the case.

4. CORRECTIONS

In [2; p. 25, line 12] the exponent $2t - r$ of q is incorrect. This exponent should be $2t - 2r$. We employ the notation of this paper and state as corrected the formula [2; p. 25, line 14] which was being developed when the error occurred.

THEOREM 2.

$$N(2m, t; 2m, 0) = q^{-1/2t(t-1)} \sum_{0 \leq 2r \leq t} q^{m(2t-2r)} S(t, 2r).$$

In [5] John Hodges developed a formula for certain exponential sums involving skew matrices. His development from the outset depended upon the results we corrected in Theorem 2. Using the methods outlined by Hodges we have redone the development of the main theorem [5; Theorem 1] and restate it here as corrected.

THEOREM 3. *If B is a skew matrix of order t and rank 2j then*

$$W(B, r) = q^{2jr} \sum_{k=0}^r (-1)^k q^{k(k-1-2j)} \begin{bmatrix} j \\ k \end{bmatrix}' S(t-2j, 2r-2k)$$

where W is described in [5; (3.1)], S is given by (2.3) and the prime indicates that q is to be replaced by q² in the q-binomial coefficients.

Hodges' results on hypergeometric sums [5; Theorem 2] and the conclusion drawn [5; p. 119, lines 1-3] will also be altered by the correction.

5. EXAMPLES

As a partial check on our results we investigate a few simple examples. We first calculate directly the number of solutions over GF(q) to the matrix equation

$$\begin{bmatrix} x & y \\ z & w \end{bmatrix}' \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x & y \\ z & w \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

the problem reduces to counting solutions over GF(q) to the equation $xw - zy = 0$. There are $q^3 + q^2 - q$ such solutions. This quantity equals the value of $N(2, 2; 2, 0)$ determined by Theorem 2.

In a similar manner we can determine the number of solutions to the matrix equation

$$\begin{bmatrix} x & y \\ z & w \end{bmatrix}' \begin{bmatrix} a & b \\ c & d \end{bmatrix}' \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x & y \\ z & w \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 1 \end{bmatrix}$$

by counting solutions over GF(q) to the equation $(ad - bd)(xw - zy) = 1$. There are $q^7 - q^6 - 2q^5 + 2q^4 + q^3 - q^2$ such solutions. This quantity equals the value $N(2, 2; 2, 0)$ which we obtain from Theorem 1.

Although we do not go through the details, it is easy to show by direct calculation that $W(B, r) = q - 1$ where B is the 2×2 zero matrix and $r = 1$. This also agrees with results obtained by appropriate substitutions in Theorem 3.

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