
ATTI ACCADEMIA NAZIONALE DEI LINCEI
CLASSE SCIENZE FISICHE MATEMATICHE NATURALI
RENDICONTI

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**Some results on a class of degenerate evolution
problems**

*Atti della Accademia Nazionale dei Lincei. Classe di Scienze Fisiche,
Matematiche e Naturali. Rendiconti, Serie 8, Vol. 66 (1979), n.1, p. 6–11.*

Accademia Nazionale dei Lincei

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Equazioni funzionali. — *Some results on a class of degenerate evolution problems.* Nota di ANGELO FAVINI^(*), presentata ^(**) dal Corrisp. G. CIMMINO.

RIASSUNTO. — Si considera una equazione di evoluzione della forma

$$\frac{d}{dt} Bx(t) = -Ax(t) + f(t), \quad t > 0, \quad \| Bx(t) - z_0 \|_X \xrightarrow{t \rightarrow 0^+} 0,$$

dove la funzione data f e la funzione incognita $x(\cdot)$ sono a valori negli spazi di Banach complessi X e Y rispettivamente, A e B sono operatori lineari chiusi da Y a X e B può non avere inverso limitato. Sono date condizioni sul risolvente B -modificato di A , che forniscono l'esistenza e l'unicità delle soluzioni. I risultati sono applicati ad alcune classi di equazioni degeneri alle derivate parziali.

1. INTRODUCTION

This note is devoted to the abstract initial value problem

$$(1.1) \quad \frac{d}{dt} Bx(t) = -Ax(t) + f(t), \quad t \in (0, +\infty) = \mathbb{R}^+,$$

$$(1.2) \quad \lim_{t \rightarrow 0^+} \| Bx(t) - z_0 \|_X = 0,$$

where A, B are linear closed operators from the complex Banach space Y into the Banach space X , with their domains $\mathcal{D}(A), \mathcal{D}(B)$ respectively, $f(\cdot)$ is a strongly continuous function from $[0, +\infty) = \overline{\mathbb{R}^+}$ into X and $z_0 \in X$ is given.

We remark that the "solution" $x(\cdot)$ of (1.1) (1.2) may have either no strong derivative or no limit, in whatever sense, as $t \rightarrow 0^+$. Hence, we shall also analyse the Cauchy problem

$$(1.3) \quad B \frac{dx(t)}{dt} (= B\dot{x}(t)) = -Ax(t) + f(t), \quad t \in (0, +\infty),$$

$$(1.4) \quad \lim_{t \rightarrow 0^+} \| x(t) - x_0 \|_Y = 0.$$

A detailed study of (1.3) in the finite-dimensional setting is to be found, for example, in [G 1] and [C 1].

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^(**) Nella seduta del 13 gennaio 1979.

In very recent times other papers and books have appeared in the literature which consider (1.3) (1.4) in the abstract case and under various hypotheses; see [B 1, C 2, C 3, D 1, S 1, Z 1].

Here we follow an approach based on Laplace transform method and thus, the location of the set of all complex numbers λ for which $\lambda B + A$ has a bounded inverse $(\lambda B + A)^{-1} = R_B(\lambda; A)$ plays a primary role. We shall see that the request for sufficiently smooth solutions involves somewhat restrictive assumptions on the data.

A detailed version with proofs of these results is to be found in [F 1].

2. DEFINITIONS. Let m be a non negative integer; we shall denote by $C^{(m)}(R^+; X)$ (respectively, $C^{(m)}(\bar{R}^+; X)$), the set of all X -valued functions defined and m -times strongly continuously differentiable on R^+ (resp., \bar{R}^+).

If f is an element of $C^{(0)}(\bar{R}^+; X)$, the Y -valued function $x(\cdot)$ will be called a strong solution of (1.1) (1.2) if $x(\cdot) \in C^{(0)}(R^+; Y)$, $x(t) \in \mathcal{D}(A) \cap \mathcal{D}(B)$ for all $t \in R^+$, $Ax(\cdot) \in C^{(0)}(R^+; X)$, $Bx(\cdot) \in C^{(1)}(R^+; X)$ and (1.1) (1.2) are verified.

$x(\cdot)$ will be said to be a classical solution of (1.3) (1.4) if $x(\cdot) \in C^{(0)}(\bar{R}^+; Y) \cap C^{(1)}(R^+; Y)$, $x(t) \in \mathcal{D}(A)$, $\dot{x}(t) \in \mathcal{D}(B)$ for every $t \in R^+$, $Ax(\cdot) \in C^{(0)}(R^+; X)$, $B\dot{x}(\cdot) \in C^{(0)}(R^+; X)$ and (1.3) (1.4) hold.

3. Uniqueness and existence of the solutions. Making use of an argument as in [K 2, p. 63], we have the following result about existence of a solution:

THEOREM 3.1. *Suppose that $R_B(\lambda; A)$ exists for all sufficiently large real λ and there are $C \in R^+$, a non negative integer k such that for the norm of $AR_B(\lambda; A)$ as a bounded operator from X into itself, we have $\|AR_B(\lambda; A)\|_{X \rightarrow X} \leq C\lambda^k$ for these λ 's. Then the strong solution of (1.1) (1.2) is unique.*

Remark 3.1. By a standard change-of-variable argument we may replace A by $A + \lambda_2 B$ where $\lambda_2 > \lambda_1$, in (1.1) or (1.3). Therefore we may assume without loss of generality that A has a bounded inverse and $\mathcal{D}(A) \subseteq \mathcal{D}(B)$. This assumption will be kept henceforth.

As regards existence, we have

THEOREM 3.2. *Suppose that $\lambda B + A$ has a bounded inverse for all complex numbers λ such that $\text{Re } \lambda \geq \alpha > 0$ and*

$$(3.1) \quad \|AR_B(\lambda; A)\|_{X \rightarrow X} \leq C(|\lambda|^k + 1), \text{Re } \lambda \geq \alpha,$$

where K is a non negative integer and C is a positive constant.

If $z_0 = B(A^{-1}B)^{k+1}z_1$; $f \in C^{(k+2)}(\bar{R}^+; X)$, $f^{(j)}(0) = \frac{d^j}{dt^j}f(0) = B(A^{-1}B)^{k-j}w_j$, $j = 0, 1, \dots, k$, with $z_1, w_j \in D(A)$, then (1.1) (1.2)

has the unique strong solution

$$\begin{aligned}
 x(t) = & \sum_{j=0}^{k+1} (-1)^j \frac{t^j}{j!} (BA^{-1})^{k-j+1} z_1 + (-1)^{k+2} Z_{k+2}(t) Az_1 + \\
 & + \sum_{j=0}^k \left\{ \sum_{s=0}^{k-j+1} (-1)^{s+1} \frac{t^{j+s}}{(j+s)!} (BA^{-1})^{k-j-s+1} w_j + (-1)^{k-j+3} Z_{k+2}(t) Aw_j \right\} + \\
 & + Z_{k+2}(t) f^{(k+1)}(0) + \int_0^t Z_{k+2}(t-s) f^{(k+2)}(s) ds, \quad t \in \mathbb{R}^+,
 \end{aligned}$$

where

$$Z_p(t) = (2\pi i)^{-1} \int_{\alpha_1 - i\infty}^{\alpha_1 + i\infty} \lambda^{-p} e^{\lambda t} R_B(\lambda; A) d\lambda, \quad p \geq k+2, \quad t \in \mathbb{R}^+,$$

and $\alpha_1 > \alpha$.

Remark 3.2. We want to give a simple example to emphasize that z_0 and f must satisfy some compatibility and regularity conditions so that the initial value problem can have a solution or be well-posed.

Let $z_0 = (x_1, y_1)$, $f = (f_1, f_2)$ be elements of $\mathbf{C}^2 = \mathbf{C} \times \mathbf{C}$ and of $\mathbf{C}^{(0)}(\overline{\mathbb{R}^+}; \mathbf{C}^2)$, respectively. Define A, B as the linear operators associated to the matrices $(a_{ij}), (b_{ij})$, $a_{11} = a_{22} = 1$, $a_{12} = a_{21} = 0$, $b_{11} = b_{21} = b_{22} = 0$, $b_{12} = 1$, respectively.

Then (1.1) (1.2) has a strong solution if we assume that $f_2 \in \mathbf{C}^{(1)}(\overline{\mathbb{R}^+}; \mathbf{C})$ and $x_1 = f_2(0)$, $y_1 = 0$, since $x(t) = f_1(t) - f_2(t)$, $y(t) = f_2(t)$.

THEOREM 3.3. *Suppose that (3.1) holds. If*

$$\begin{aligned}
 x_0 = & (A+1)B^{k+2} x_1, \quad x_1 \in \mathcal{D}(A), \quad f \in \mathbf{C}^{(k+3)}(\overline{\mathbb{R}^+}; \mathbf{X}), \\
 f^{(j)}(0) = & B(A^{-1}B)^{k+1-j} z_j, \quad z_j \in \mathcal{D}(A), \quad j = 0, 1, \dots, k+1,
 \end{aligned}$$

then (1.3) (1.4) has a classical solution.

If (3.1) is satisfied with $k=0$ on all of \mathbf{C}^+ , the set of all complex numbers with positive real parts, it is possible to obtain a refinement of Theorem 3.2. In fact, we are in a nearly-analytic case.

It is not too difficult to see that $R_B(\lambda; A)$ has then an analytic extension on $S_\omega: |\arg \lambda| < \omega$, $\pi/2 < \omega < \pi$, and an estimate as (3.1) is retained on $S_{\omega-\varepsilon}$. Define

$$Z_j(t) = (2\pi i)^{-1} \int_{\Gamma} e^{\lambda t} \lambda^{-j} R_B(\lambda; A) d\lambda, \quad j = 0, 1, \dots,$$

where Γ is a suitable contour in $S_{\omega-\varepsilon}$, $0 < \varepsilon < \omega - \pi/2$, coinciding with the rays $|\arg \lambda| = \omega - \varepsilon$, for $|\lambda| > \text{const.}$, and avoiding the origin to the right. We have

THEOREM 3.4. *Suppose that the foregoing hypotheses are satisfied. If z_0 belongs to the closure of $B(\mathcal{D}(A))$ and $f \in C^{(2)}(\bar{R}^+; X)$, then (1.1) (1.2) has the unique strong solution*

$$x(t) = Z_0(t)z_0 + \sum_{j=1}^2 Z_j(t)f^{(j-1)}(0) + \int_0^t Z_2(t-s)f^{(2)}(s) ds, t \in R^+.$$

If $Ax_0 = Bx_1, x_1 \in \mathcal{D}(A), f \in C^{(3)}(\bar{R}^+; X), f(0) = B\omega, \omega \in \mathcal{D}(A)$, then

$$x(t) = x_0 + t(\omega - x_1) - Z_2(t)(\omega - x_1) + \sum_{j=2}^3 Z_j(t)f^{(j-1)}(0) + \int_0^t Z_3(t-s)f^{(3)}(s) ds$$

is a classical solution of (1.3) (1.4).

Next theorem concerns the finite dimensional case. By use of the spectral representation of a linear operator as given in [K I, p. 41], we obtain

THEOREM 3.5. *Suppose that $X = Y = C^n$ and $f \in C^{(m_1-1)}(\bar{R}^+; X)$, where m_1 is the algebraic multiplicity of 0 as an eigenvalue of BA^{-1} .*

Let $\lambda_1 = 0, \lambda_2, \dots, \lambda_s$, be the distinct eigenvalues of BA^{-1} and define

$$Q_k = -(2\pi i)^{-1} \int_{\gamma_k} (zA + B)^{-1} dz, k = 1, \dots, s,$$

where γ_k is a positively-oriented small circle enclosing $-\lambda_k$ and excluding $-\lambda_j, j \neq k$. Then the general solution of (1.1) is given by

$$x(t) = \sum_{j=0}^{m_1-1} (-1)^j A^{-1} (BQ_1)^j A Q_1 f^{(j)}(t) + \sum_{k=2}^s \{A^{-1} e^{-t(BQ_k)^{-1}} A Q_k w + \int_0^t A^{-1} e^{-(t-s)(BQ_k)^{-1}} (BQ_k)^{-1} A Q_k f(s) ds\}, w \in X.$$

In particular, if $m_1 = 1$, then (1.1) (1.2) has a unique strong solution for all z_0 in the range of B and $f \in C^{(0)}(\bar{R}^+; X)$.

4. *Applications.* Let $A(x, D), B(x, D)$ be strongly elliptic operators in a bounded domain Ω of R^n with coefficients continuous in $\bar{\Omega}$ and let $\partial\Omega$ be of class C^{2m} :

$$A(x, D) = \sum_{|\alpha| \leq 2m} a_\alpha(x) D^\alpha, B(x, D) = \sum_{|\beta| \leq 2p} b_\beta(x) D^\beta.$$

Suppose $p < m$ and $A(x, D)$ uniformly strongly elliptic.

If A, B are the operators defined in $L^q(\Omega), q \geq 1$, by $(Au)(x) = A(x, D)u(x), (Bv)(x) = B(x, D)v(x), u \in \mathcal{D}(A) = H^{2m,q}(\Omega; \{B_j\}), v \in \mathcal{D}(B) = H^{2p,q}(\Omega; \{C_j\}), [F 2, p. 75]$, and $(A, \{B_j\}, \Omega)$ is a regular elliptic

boundary problem, there is $\varepsilon_1 \in \mathbb{R}^+$ such that for all $0 < \varepsilon < \varepsilon_1$, the estimate $\|B(x, D)u\|_{L^q(\Omega)} \leq \varepsilon \|A(x, D)u\|_{L^q(\Omega)} + C\varepsilon^{-p(m-p)^{-1}} \|u\|_{L^q(\Omega)}$, $u \in C^{(2m)}(\bar{\Omega})$ holds.

On the other hand, we have

LEMMA 4.1. *Suppose that $\|R_B(\lambda; A)\|_{X \rightarrow Y} \leq C|\lambda|^l$, $\operatorname{Re} \lambda \geq \alpha$, where l is a non negative integer. If there are a positive integer m and $C \in \mathbb{R}^+$ such that for all $\varepsilon \in \mathbb{R}^+$*

$$\|Bx\|_X \leq \varepsilon \|Ax\|_X + C\varepsilon^{-m} \|x\|_Y, \quad x \in D(A),$$

then $\|AR_B(\lambda; A)\|_{X \rightarrow X} \leq C|\lambda|^{l+m+1}$, $\operatorname{Re} \lambda \geq \alpha$.

LEMMA 4.2. *Let $X = Y$ be and suppose that there are a positive function $C(\lambda)$ on $\operatorname{Re} \lambda \geq \alpha > 0$ and a domain W of \mathbb{C} containing the origin, so that*

$$(4.1) \quad \|(\mu + \lambda B + A)x\|_X \geq C(\lambda) \|x\|_X, \quad x \in D(A), \quad \mu \in W.$$

Further, for any $\operatorname{Re} \lambda \geq \alpha$ we assume that a $\mu(\lambda) \in W$ can be found such that $\mu(\lambda) + \lambda B + A$ has a bounded inverse.

Then $R_B(\lambda; A)$ exists for $\operatorname{Re} \lambda \geq \alpha$ and $\|R_B(\lambda; A)\|_{X \rightarrow Y} \leq C(|\lambda|)^{-1}$.

For example, if $X = Y$ is a Hilbert space with inner product $\langle \cdot, \cdot \rangle$, and $\langle Bx, x \rangle \geq 0$, $\operatorname{Re} \langle Ax, x \rangle \geq m_0 \|x\|^2$, $m_0 \in \mathbb{R}^+$, $x \in \mathcal{D}(A)$, then (4.1) is satisfied with $W = \{\mu \in \mathbb{C}; \operatorname{Re} \mu > -m_0/2\}$ and $C(\lambda) = m_0/2$.

In view of these results, we can handle problems of the type

$$\frac{\partial}{\partial t} B(x, D)u(t, x) + A(x, D)u(t, x) = f(t, x), \quad (t, x) \in \mathbb{R}^+ \times \Omega,$$

$$B_j(x, D)u = 0, \quad x \in \partial\Omega, \quad 1 \leq j \leq m,$$

$$\lim_{t \rightarrow 0^+} B(x, D)u(t, x) = v_0(x), \quad x \in \Omega.$$

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